

# Faseeh Ahmad

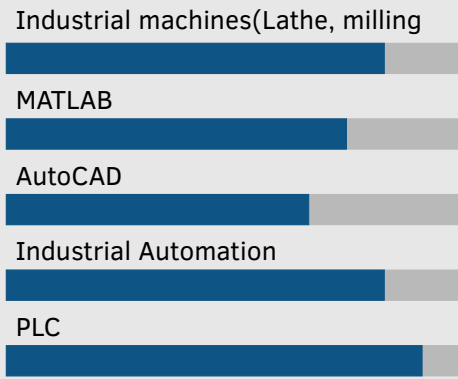
Mechatronics Engineer

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## About me

Enthusiastically seeking experience in the field of Mechatronics Engineering and desire to work with established organizations in order to strengthen my skills and knowledge in the best interests of the organization and for my personal professional growth. A communicative, encouraging team player who presents ideas effectively and is able to assist others in the latest procedures. A keen learner and willing to work with a team and separate individuals to help achieve required goal.

## Skills



Leader\*6 Sarcastic\*5 \*

(\*)[The skill scale is from 0 (Fundamental Awareness) to 6 (Expert).]

## Interests

Robotics and Industrial Automation  
Basketball  
Chess.

## Education

2019	BE Mechatronics Air University,Islamabad	Mechatronics Engineering
2013	FSC PreEngineering	APSACS Jhelum
2011	SSC Majoring in Computer Science	APSACS

## Awards and Certifications

2019	Self Driving Cars , University of Toronto
2018	Semi-Finalist , Air-Tech Robotics Competition
2017	Gold Medalist ,Athletics.
2017-2019	Air University Basketball Team
2018	Chess Team Leader.

## Experience

2019	E-commerce Officer iGate Technologies	Employee
2015	NCR Karachi	Intern
2017	FFC Mirpur Mathelo	Intern
2017-2018	President of Air University Robotics Society head of Robotics And Automation society Air University	Society Head
2017-2019	Article Writer	Freelancer

## NOTABLE PROJECTS

Title: Explosive Ordnance Disposal Robot  
Description: The purpose of the EOD or more commonly known as bomb disposal robot is to dispose a threat package wirelessly with the help of an end user.

Title: Research Paper  
Description: A research paper was written of 56 pages about my final year project which is being published on IEEE.

Title: Banking Management System  
Description : In This Project Banking Management System was made in Microsoft Visual Studio , which contained employees data,Packages and other data.

Title: Conveyor belt  
Description: A conveyor belt was made using Arduino as a micro controller to separate big and small bottles and discard broken ones.

Title: Autonomous Path Following and Navigating Robot  
Description : In This project An Autonomous Robot was made which is able to make its own path , avoid obstacle , Follow wall , Sense Color , Navigate and reach the other side of the same color and blow the balloon.